



Séminaire Modélisation et Calcul Scientifique
Irène Vignon-Clémentel & Martin Vohralik orgs.
INRIA Rocquencourt – October 1 2013

Toward live CFD-computing interaction and visualization using GPU acceleration

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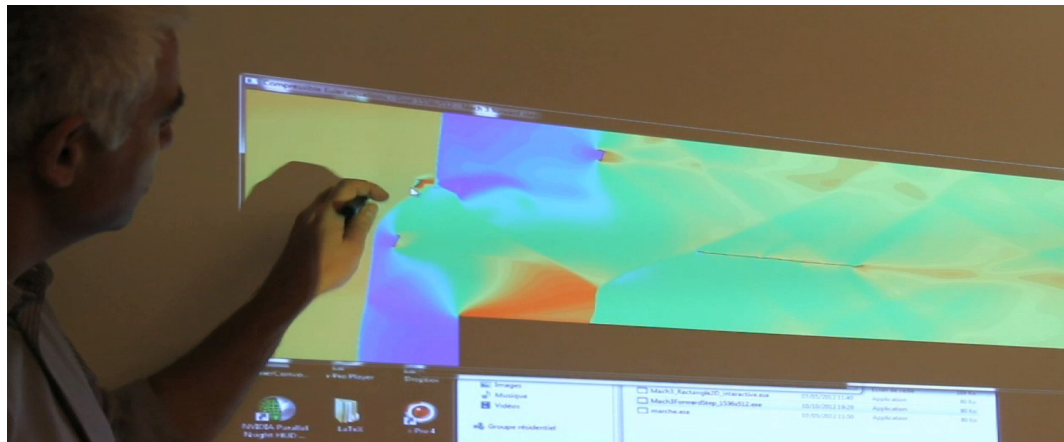
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NVIDIA CUDA Research Center ENS CACHAN

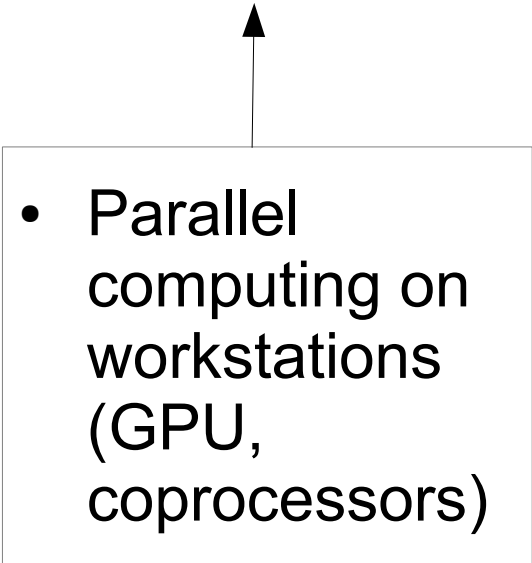
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Objectives

- Get PDE approximate solutions instantaneously (« real time », co-simulation)
- Be able to directly act on the computations



Possible tracks ...

- Reduced-order modeling (POD, PGD, reduced basis method)
 - High performance (parallel) computing
 - Efficient algorithms, new paradigms (Lattice Boltzmann, ...)
 - Multilevel modeling, surrogates
 - Parallel computing on workstations (GPU, coprocessors)
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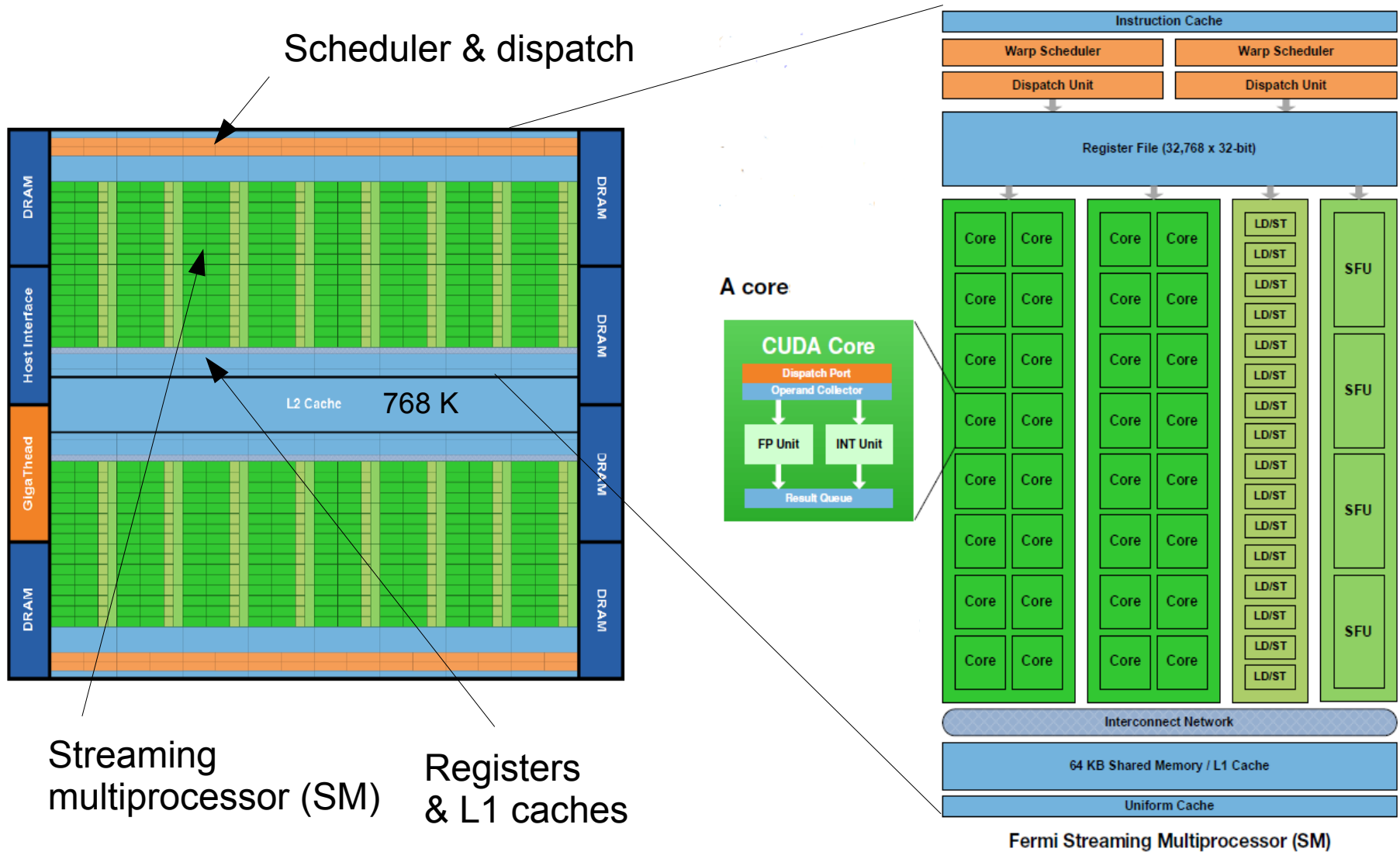
Toward GPU computing for PDE pbs – Outline

1. GPU hardware architecture
2. Performance drivers
3. Focus on Lattice Boltzmann Methods (LBM)
4. Real time flow interaction
5. Work in progress : LB thermal-fluid Boussinesq system
6. Suspension flows

Perspectives

1. GPU hardware architecture

nVIDIA GPU *FERMI* compute architecture



(courtesy of Nvidia)

NVIDIA – KEPLER family (2013)

NVIDIA GeForce GTX 690 (game)

- 2 x 1536 cores, 300 W
- 8 streaming multiprocessors (SM)
- Memory bandwidth 192 GB/sec
- MEM 4 GB (2048 MB per GPU)
- DRAM bus memory 512-bit GDDR5
- 2x1.8 Tflops SP, 2x130 Gflops DP



NVIDIA TESLA K20X (HPC)

- **2688 cores**, 250W !
- 14 streaming multiprocessors (SM)
- Memory bandwidth 250 GB/sec
- MEM 6 GB
- 3.95 Tflops SP, **1.31 Tflops DP !**



2. GPU Performance drivers

Performance drivers

- Multiprocessor **occupancy**
- **Byte-per-flop** ratio (mem bandwidth vs FP operations)
- **Memory** management : registers, cache, coalesced read/write memory, fixed neighboring patterns reads/writes
- Warp **divergence** : be careful to trees of conditional branches
- Communication : host-to-device **PCIe** bus bottleneck

[Williams et al., **Roofline** : an insightful visual performance model for multicore architectures, Com. ACM, 2009]

Questions for the design of numerical methods :

- **Explicit** vs implicit ?
- **Cartesian** vs unstructured grid ?
- Order of accuracy vs grid size ?
- Specific vs **undifferentiated** treatment ? (interfaces, ...)
- Boundary conditions: **embedded** strategy ?
- How to achieve **condensed stencil** ?
- Operator splitting, **alternating** directions
- Change the **model description** ?
- Replace spatial derivatives by time derivative, particle derivative ? ...

3. Focus on Lattice Boltzmann methods (LBM)

Lattice BGK (LBGK) model

Based on a simple discretization of the Boltzmann equation with BGK approximation for the collision term :

$$f(x + ce_i \Delta t, e_i, t + \Delta t) - f(x, e_i, t) = \frac{1}{\tau} [f_i^{eq}(\rho, \mathbf{u}) - f(x, e_i, t)]$$

Relaxation BGK « collision » term

Lattice Knudsen number

$$c = \frac{\Delta x}{\Delta t}$$

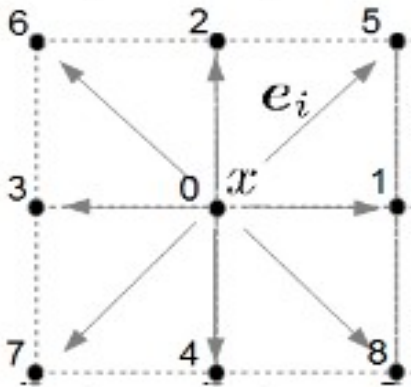
$$e_0 = 0, e_1 = (1, 0), e_2 = (1, 1), \dots$$

Moments:

$$\sum_{i \in \mathcal{S}} f(x, e_i, t) = \rho(x, t),$$

$$\sum_{i \in \mathcal{S}} ce_i f(x, e_i, t) = \rho \mathbf{u}(x, t).$$

D2Q9
lattice



Lattice D2Q9 BGK model

- D2Q9 unknowns $f_i(x, t) \equiv f(x, c\mathbf{e}_i, t), i \in \{0, \dots, 8\}$.
- LB equation

$$f_i(x + c\mathbf{e}_i, t + \Delta t) = f_i(x, t) + \omega [f_i^{eq}(\rho(x, t), \mathbf{u}(x, t)) - f_i(x, t)]$$

- Requirements

$$\omega = \frac{1}{\tau}$$

$$\sum_{i \in \mathcal{S}} f_i^{eq}(\rho, \mathbf{u}) = \rho,$$

$$\sum_{i \in \mathcal{S}} c\mathbf{e}_i f_i^{eq}(\rho, \mathbf{u}) = \rho \mathbf{u},$$

$$\sum_{i \in \mathcal{S}} c^2 \mathbf{e}_i \otimes \mathbf{e}_i f_i^{eq}(\rho, \mathbf{u}) = \rho \mathbf{u} \otimes \mathbf{u} + pI$$

+ some discrete symmetry/
invariance conditions

Practical implementation « *stream-and-collide* »

1. Streaming step

$$\tilde{f}_i(x, t) = f_i(x + c\mathbf{e}_i, t)$$

2. Collision step

- Compute the moments $(\rho, \rho\mathbf{u})(x, t) = \sum_{i \in \mathcal{S}} (1, c\mathbf{e}_i) \tilde{f}_i(x, t)$

- Compute the equilibrium function $\tilde{f}_i^{eq} = \rho w_i [\dots]$

- Time advance




$$f_i(x, t + \Delta t) = \tilde{f}_i(x, t) + \omega \left[\tilde{f}_i^{eq}(\rho(x, t), \mathbf{u}(x, t)) - \tilde{f}_i(x, t) \right]$$

- **Explicit method**
- **Underlying cartesian grid**
- **Fixed (small) stencil**
- **Elementary operations**
- **Very easy to implement**

Particularly suitable for GPU computing

4. Real time visualization & flow interaction

Visualization & interaction

- Direct GPU compute/visualization binding (Pixel Buffer Object PBO) + OpenGL
- Dynamic mask array for adding/removing wall BC
- IR U-Pointer device for large screen interaction (seminars, conferences)

-  Android tablets for controls & GUI. Use of OSC for bidirectional communication between GPU-workstation and tablet (coll. K. Labourdette).

5. Work in progress : LB thermal-fluid Boussinesq system

Thermal + CFD coupling : Boussinesq model

$$\nabla \cdot \mathbf{u} = 0,$$

$$\partial_t \mathbf{u} + \mathbf{u} \cdot \nabla \mathbf{u} + \nabla p - \frac{\mu}{\rho_0} \Delta \mathbf{u} = \mathbf{g} (1 - \beta(T - T_0)),$$

$$\partial_t T + \mathbf{u} \cdot \nabla T - \nabla \cdot (\kappa \nabla T) = 0,$$

$$+IC + BC.$$

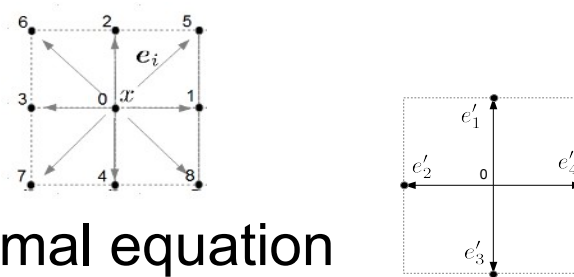
$$\mu, \alpha, \kappa > 0.$$

Convection, diffusion, source term, coupling.

2D Lattice Boltzmann discretization

$$c = \frac{\Delta x}{\Delta t}.$$

- D2Q9 LBGK lattice for fluid
- D2Q4 LBGK lattice for the thermal equation



Half-discretization (continuous in time) :

$$\partial_t f_i + c \mathbf{e}_i \cdot \nabla_x f_i = \frac{f_i^{eq} - f_i}{\tau \Delta t} - \frac{\mathbf{e}_i \cdot \mathbf{g}}{2c} (1 - \beta(T - T_0))$$

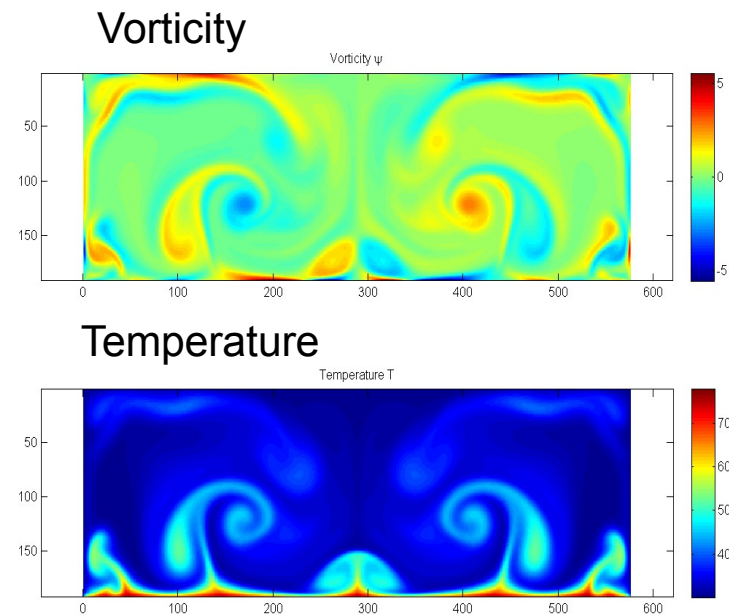
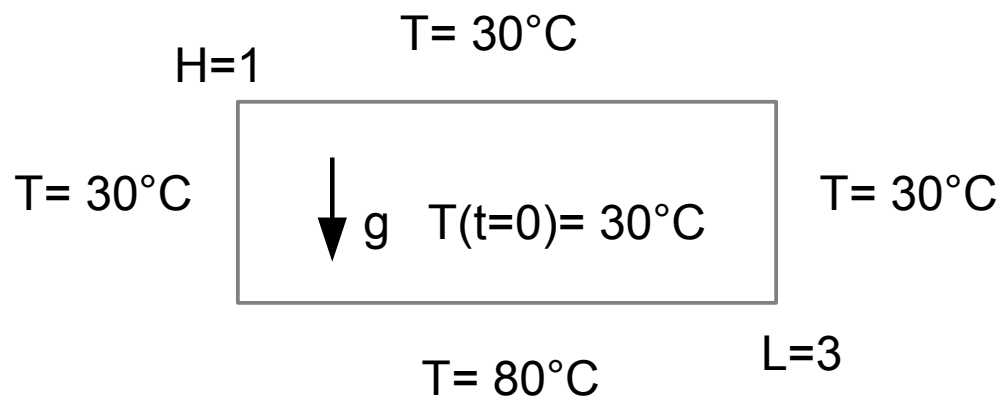
$$(\rho, \mathbf{u}) = \sum_{i=0}^8 (1, \mathbf{e}_i) f_i, \quad f_i^{eq} = f_i^{eq}(\rho, \mathbf{u})$$

$$\partial_t k_i + c \mathbf{e}'_i \cdot \nabla_x k_i = \frac{k_i^{eq} - k_i}{\tau' \Delta t}$$

$$T = \sum_{i=1}^4 k_i, \quad k_i^{eq} = \frac{T}{4} \left(1 + 2 \frac{\mathbf{u} \cdot \mathbf{e}'_i}{c} \right).$$

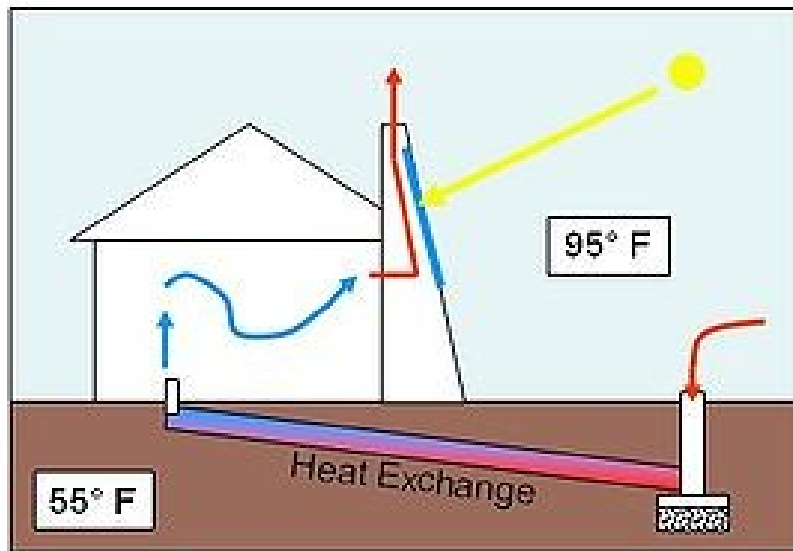
Validation of the method

$$g = 9.81, Re = 2300, Pr = 0.71, Ra = 3 \cdot 10^5, \nu = Re^{-1}, \kappa = \frac{\nu}{Pr}, \beta = \frac{Ra \nu \kappa}{g H^3 \Delta T}$$



Collaborators : S. Faure, L. Gouarin, B. Graille
(U. Paris-Sud Orsay)

Forseseen application : solar powered air conditioning

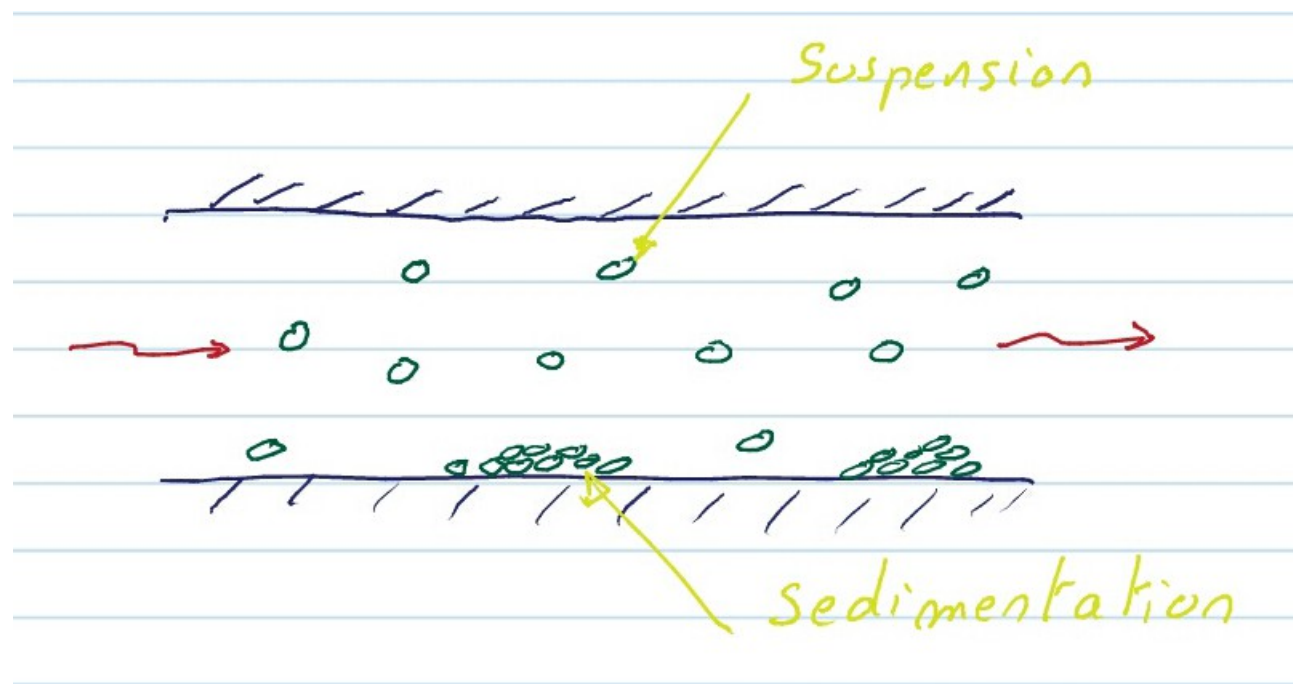


Design the chimney shape in order to reduce recirculating zones at the top and maximize the flow rate

(see [Chenier et al.], [Le Quéré, Sergent & co-workers] on the subject)

Work in progress

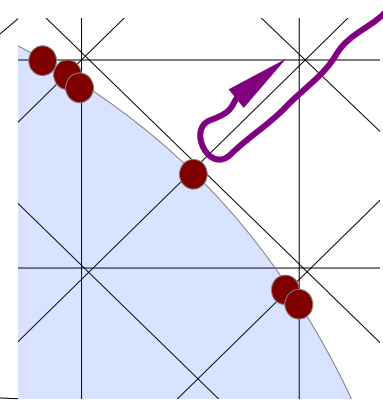
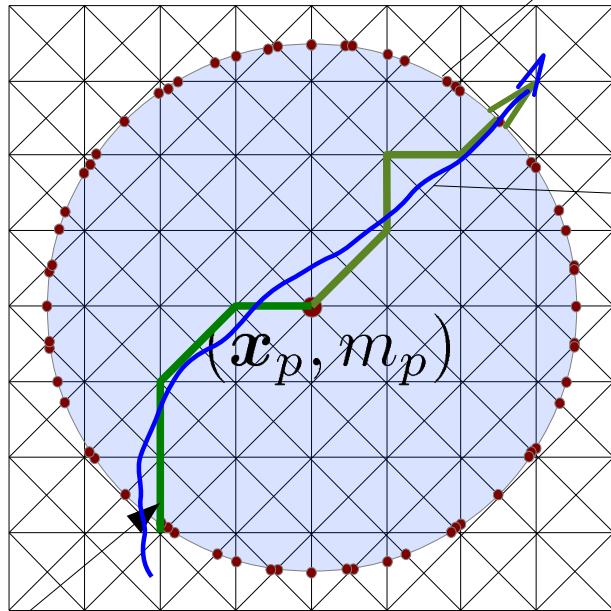
6. Suspension / sediment gravity flows



Suspension flows

Boundary conditions, flux formulation

[Dubois, Lallemand 2008]



Conservative coupling

$$\frac{d\mathbf{x}_p}{dt} = \mathbf{u}_p,$$

$$m_p \frac{d\mathbf{u}_p}{dt} = \int_{\partial S_p} \underline{\underline{\Sigma}} \nu d\sigma.$$

Exact trajectory approximated by a broken-line lattice path
(random choice stochastic method)

==> Geometric elements and intersecting nodes computed once-for-all

Tensor computed from 2nd-order discrete moments

Perspectives

- Euler-Euler multiphase flows (suspension)
- Immiscible fluids with moving interfaces
- NVIDIA outlook : 20 Tflops DP/GPU by 2018
→ real-time interactive 3D ?
- CPU-GPU convergence (be aware) ...

Acknowledgments

- NVIDIA CUDA Research Center ENS Cachan
- Institut fédératif FARMAN ENS Cachan
- Labex LMH Fondation Mathématique Hadamard FMJH